## Manual changing position actuators Siko

In case position actuator(s) from Siko type "AG05" need to be changed please follow carefully all steps as mentioned below:

- 1. Switch on the machine with the original actuator(s) and look up the "Can-adres" and "actual position" of the actuator(s) to be replaced:
  - a. The Can-address is the mentioned number in the screen "Settings": (f.e. 1=saw;2=bottem ten.head vert....)

Select Spindle					
- *	High F	3.Top TenH Vert.	anguage: ENGLISH		
i arman		4.Top TenH Hor	1.Saw Hor		
		2.Bot.TenH. Vert.	Fence		
8.Spindle2 Vert	6.Spindle1 Vert	5.Bot.TenH Hor	7-		
9.Spindle2 Hor	7.Spindle1 Hor		➡		
Table setpoints Table posit					

b. The actual position can be found once the corresponding motor is selected under settings:

Instellingen as							
	ABCDEFGHIJKLMNOPQRSTUVWXYZ						
Actual P	osition -00000000.0 mm	Limit Positive	0000000.00 mm				
	Target 0000000.00 mm		0000000.00 mm				
Can Error		In Position Window	0000000.00 mm				
No Error		Backlash	00.00 mm				
Disabled		Velocity Manual	000 rpm				
Man Neg	Man Pos	Velelocity Positioning	000 rpm				
Start	Reset	Reset Position to	0000.00 m				
		Cancel/Reload	ОК				

2. Switch the machine off and replace the positioning motor(s) that need replacement

3. Disconnect the Can-connector from the touch screen:



4. Switch on the machine again and install for every replaced motor the Can adress with the keys of the display at the back of the motor:



- a. Press the " \* " key until the display changes to "Para ChPar"
- b. Press the " \* " key , the display changes to "Pin"
- c. Press the " \* " key , the display changes to "Para Quit"
- d. Press the left key (Up) , the display changes to "Para Bus"
- e. Press the "\*" key , the display changes to "ID" with the actual Can adress on the lower display
- f. Press the left key (Up) until the Can adress corresponds with the number you've written down in point 1.a
- g. Confirm this number by pressing the " \* " key , the display changes to "baud 500"
- h. Press the " \* " key , the display changes to "Para Quit"
- i. Press the " \* " key
- j. Repeat point a to i for the next motor(s)
- 5. Switch off the machine and plug in the Can-connector again (see point3)
- 6. Switch on the machine, Press "Login" and enter the code 3854.

- 7. Select Settings and enter for every replaced motor the value of the actual position that you've written down in point 1.b as follows:
  - a. Enter the value at the marked position
  - b. Press "Reset Position to" to copy this value to the actual position

ABCDEFGHIJKLMNOPQRSTUVWXYZ						
Actual Position -00000000.0 mm		0000000.00	mm			
Target .0000000.00 mm		0000000.00	mm			
	In Position Window	0000000.00	mm			
	Backlash	00.00	mm			
	Velocity Manual	000	rpm			
Man Pos	Velelocity Positioning	000	rpm			
Reset	Reset Position to		00 m			
	Cancel/Reload	ОК				
	ABCDEFGHIJKLMNO	ABCDEFGHIJKLMNOPQRSTUVWXYZ ition -00000000.0 mm Limit Positive arget 00000000.00 mm Limit Negative In Position Window Backlash Velocity Manual Velelocity Positioning Reset Reset Position to Cancel/Reload	ABCDEFGHIJKLMNOPQRSTUVWXYZ ition -0000000.0 mm Limit Positive 0000000.00 arget 000000000 mm Limit Negative 0000000.00 In Position Window 0000000.00 Backlash 00.00 Velocity Manual 000 Velocity Positioning 000 Reset Reset Position to 00000.00 Cancel/Reload OK			